

## MICROPOWER PHASE-LOCKED LOOP

- QUIESCENT CURRENT SPECIFIED TO 20V FOR HCC DEVICE
- VERY LOW POWER CONSUMPTION :  $100\mu W$  (TYP.) AT VCO  $f_0 = 10kHz$ ,  $V_{DD} = 5V$
- OPERATING FREQUENCY RANGE : UP TO 1.4MHz (TYP.) AT V<sub>DD</sub> = 10V
- LOW FREQUENCY DRIFT : 0.06%/°C (typ.) AT V<sub>DD</sub> = 10V
- CHOICE OF TWO PHASE COMPARATORS :
  1) EXCLUSIVE OR NETWORK
  2) EDGE-CONTROLLED MEMORY NETWORK
  WITH PHASE-PULSE OUTPUT FOR LOCK INDICATION
- HIGH VCO LINEARITY : 1% (TYP.)
- VCO INHIBIT CONTROL FOR ON-OFF KE-YING AND ULTRA-LOW STANDBY POWER CONSUMPTION
- SOURCE-FOLLOWER OUTPUT OF VCO CONTROL INPUT (demod. output)
- ZENER DIODE TO ASSIST SUPPLY REGULA-TION
- 5V, 10V AND 15V PARAMETRIC RATING
- INPUT CURRENT OF 100nA AT 18V AND 25°C FOR HCC DEVICE
- 100% TESTED FOR QUIESCENT CURRENT
- MEETS ALL REQUIREMENTS OF JEDEC TEN-TATIVE STANDARD N°. 13A, "STANDARD SPECIFICATIONS FOR DESCRIPTION OF "B" SERIES CMOS DEVICES"

#### DESCRIPTION

The **HCC4046B** (extended temperature range) and **HCF4046B** (intermediate temperature range) are monolithic integrated circuits, available in 16-lead dual in-line plastic or ceramic package. The **HCC/HCF4046B** COS/MOS Micropower Phase-Locked Loop (PLL) consists of a low-power, linear voltage-controlled oscillator (VCO) and two different phase comparators having a common signal-input amplifier and a common comparator input. A 5.2V zener diode is provided for supply regulation if necessary.



#### **VCO Section**

The VCO requires one external capacitor C1 and one or two external resistors (R1 or R1 and R2). Resistor R1 and capacitor C1 determine the frequency range of the VCO and resistor R2 enables the VCO to have a frequency offset if required. The high input impedance ( $10^{12\Omega}$ ) of the VCO simplifiers the design of low-pass filters by permitting the designer a wide choice of resistor-to-capacitor ratios. In order not to load the low-pass filter, a source-follower output of the VCO input voltage is provided at terminal 10 (DE-MODULATED OUTPUT). If this terminal is used, a load resistor (Rs) of 10 kΩ or more should be connected from this terminal to Vss. If unused this terminal should be left open. The VCO can be connected either directly or through frequency dividers to the comparator input of the phase comparators. A full COS/MOS logic swing is available at the output of the VCO and allows direct coupling to COS/MOS frequency dividers such as the HCC/HCF4024B, HCC/HCF4018B, HCC/HCF4020B,

HCC/HCF4022B, HCC/HCF4029B, and

**HBC/HBF4059A**. One or more **HCC/HCF4018B** (Presettable Divide-by-N Counter) or **HCC/HCF4029B** (Presettable Up/Down Counter), or **HBC/HBF4059A** (Programmable Divide-by-"N" Counter), together with the **HCC/HCF4046B** (Phase-Locked Loop) can be used to build a micropower low-frequency synthesizer. A logic 0 on the INHIBIT input "enables" the VCO and the source follower, while a logic 1 "turns off" both to minimize stand-by power consumption.

#### **Phase Comparators**

The phase-comparator signal input (terminal 14) can be direct-coupled provided the signal swing is within COS/MOS logic levels [logic "0"  $\leq$  30 %  $(V_{DD} - V_{SS})$ , logic "1"  $\geq$  70 %  $(V_{DD} - V_{SS})$ ]. For smaller swings the signal must be capacitively coupled to the self-biasing amplifier at the signal input. Phase comparator I is an exclusive-OR network ; it operates analogously to an over-driven balanced mixer. To maximize the lock range, the signal-and comparator-input frequencies must have a 50% duty cycle. With no signal or noise on the signal input, this phase comparator has an average output voltage equal to  $V_{DD}/2$ . The low-pass filter connected to the output of phase comparator I supplies the averaged voltage to the VCO input, and causes the VCO to oscillate at the center frequency (f<sub>o</sub>). The frequency range of input signals on which the PLL will lock if it was initially out of lock is defined as the frequency capture range  $(2 f_c)$ . The frequency range of input signals on which the loop will stay locked if it was initially in lock is defined as the frequency lock range (2 fL). The capture range is  $\leq$  the lock range. With phase comparator I the range of frequencies over which the PLL can acquire lock (capture range) is dependent on the low-pass-filter characteristics, and can be made as large as the lock range. Phase-comparator I enables a PLL system to remain in lock in spite of high amounts of noise in the input signal. One characteristic of this type of phase comparator is that it may lock onto input frequencies that are close to harmonics of the VCO center-frequency. A second characteristic is that the phase angle between the signal and the comparator input varies between 0° and 180°, and is 90° at the center frequency. Fig. (a) shows the typical, triangular, phase-to-output response characteristic of phase-comparator I. Typical waveforms for a COS/MOS phase-locked-loop employing phase comparator I in locked condition of fo is shown in fig. (b). Phase-comparator II is an edge-controlled digital memory network. It consists of four flip-flop stages, control gating, and a three-stage output-circuit comprising p- and n-type drivers having a common output node. When the p-MOS or n-MOS drivers are ON they pull the output up to V<sub>DD</sub> or down to V<sub>SS</sub>, respectively. This type of phase comparator acts only on the positive edges of the signal and comparator inputs. The duty cycles of the signal and comparator inputs are not important since positive transitions control the PLL system utilizing this type of comparator. If the signal-input frequency is higher than the comparator-input frequency, the p-type output driver is maintained ON most of the time, and both the n- and p-drivers OFF (3 state) the remainder of the time. If the signal-input frequency is lower than the comparator-input frequency, the n-type output driver is maintained ON most of the time, and both the n- and p-drivers OFF (3 state) the remainder of the time. If the signal and comparator-input frequencies are the same, but the signal input lags the comparator input in phase, the n-type output driver is maintained ON for a time corresponding to the phase difference. If the signal and comparatorinput frequencies are the same, but the comparator input lags the signal in phase, the p-type output driver is maintained ON for a time corresponding to the phase difference. Subsequently, the capacitor voltage of the low-pass filter connected to this phase comparator is adjusted until the signal and comparator inputs are equal in both phase and frequency. At this stable point both p- and n-type output drivers remain OFF and thus the phase comparator output becomes an open circuit and holds the voltage on the capacitor of the low-pass filter constant. Moreover the signal at the "phase pulses" output is a high level which can be used for indicating a locked condition. Thus, for phase comparator II, no phase difference exists between signal and comparator



input over the full VCO frequency range. Moreover, the power dissipation due to the low-pass filter is reduced when this type of phase comparator is used because both the p- and n-type output drivers are OFF for most of the signal input cycle. It should be noted that the PLL lock range for this type of phase comparator is equal to the capture range, independent of the low-pass filter. With no signal present at the signal input, the VCO is adjusted to its lowest frequency for phase comparator II. Fig. (c) shows typical waveforms for a COS/MOS PLL employing phase comparator II in a locked condition.

Figure a : Phase-Comparator I Characteristics at Low-Pass Filter Output.







Figure C : Typical Waveforms For COS/MOS Phase-locked Loop Employing Phase Comparator II In Locked Condition.





#### **FUNCTIONAL DIAGRAM**



#### **ABSOLUTE MAXIMUM RATINGS**

Symbol	Parameter	Value	Unit
V <sub>DD</sub> *	Supply Voltage : HCC Types HCF Types	- 0.5 to + 20 - 0.5 to + 18	V V
Vi	Input Voltage	- 0.5 to V <sub>DD</sub> + 0.5	V
lı –	DC Input Current (any one input)	± 10	mA
P <sub>tot</sub>	Total Power Dissipation (per package) Dissipation per Output Transistor for $T_{op}$ = Full Package-temperature Range	200	mW mW
T <sub>op</sub>	Operating Temperature : HCC Types HCF Types	- 55 to + 125 - 40 to + 85	°C ℃
T <sub>stg</sub>	Storage Temperature	– 65 to + 150	°C

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for external periods may affect device reliability.

 $^{\ast}$  All voltage values are referred to  $V_{\text{SS}}$  pin voltage.

#### **RECOMMENDED OPERATING CONDITIONS**

Symbol	Parameter	Value	Unit
V <sub>DD</sub>	Supply Voltage : HCC Types	3 to 18	V
	HCF Types	3 to 15	V
VI	Input Voltage	0 to V <sub>DD</sub>	V
Т <sub>ор</sub>	Operating Temperature : HCC Types HCF Types	– 55 to + 125 – 40 to + 85	° ℃ ℃



			Т	Test Conditions			Value							
Symbol	Parame	ter	V	Vo	llol	VDD	TL	ow*		25°C		T <sub>Hi</sub>	ah*	Unit
· ·			(V)	(V)	(μA)	(V)	Min.	Max.	Min.	Typ.	Max.	Min.	Max.	
VCO S	ECTION												JØ	
V <sub>он</sub>	Output High	<u>ו</u>	0/5		< 1	5	4.95		4.95	5		4.95		
011	Voltage		0/10		< 1	10	9.95		9.95	10		9.95	1	
	U		0/15		< 1	15	14.95		14.95	15		14.95	1	
V <sub>OL</sub>	Output Low	1	5/0		< 1	5		0.05			0.05		0.05	V
	Voltage		10/0		< 1	10		0.05			0.05		0.05	
			15/0		< 1	15		0.05			0.05		0.05	
I <sub>он</sub>	Output		0/5	2.5		5	- 2		- 1.6	- 3.2		- 1.15		
	Drive	HCC	0/5	4.6		5	- 0.64		- 0.51	- 1		- 0.36		
	Current	Types	0/10	9.5		10	- 1.6		- 1.3	- 2.6		- 0.9		
			0/15	13.5		15	- 4.2		- 3.4	- 6.8		- 2.4		
			0/5	2.5		5	- 1.53		- 1.36	- 3.2		- 1.1		
		HCF	0/5	4.6		5	- 0.52		- 0.44	- 1		- 0.36		
		Types	0/10	9.5		10	- 1.3		- 1.1	- 2.6		- 0.9		
		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	0/15	13.5		15	- 3.6		- 3.0	- 6.8		- 2.4		mΑ
	Output		0/5	0.4		5	0.64		0.51	1		0.36		
.01	Sink	HCC	0/10	0.5		10	16		1.3	26		0.9		
	Current	Types	0/15	1.5		15	4.2		3.4	6.8		24		
			0/5	0.4		5	0.52		0.44	1		0.36		
		HCF	0/10	0.4		10	1.3		1 1	26		0.00		
		Types	0/10	1.5		15	1.5		1.1	2.0		0.9		
Lux Lu	Input	LCC	0/15	1.5		15	3.0		3.0	0.0		2.4		
' H,   ∟	l eakage	Types	0/18			18		± 0.1		$\pm 10^{-5}$	± 0.1		± 1	
	Current	HOF		Any In	put					-				μA
	Carron	Types	0/15			15		± 0.3		± 10 <sup>-5</sup>	± 0.3		± 1	
PHASE		TOR S	ECTI	ON									iI	
	Total Device	<u>.</u>	0/5			5		0.1		0.05	0.1		01	
100	Current	•	0/10			10		0.1		0.00	0.5		0.1	
	Pin $14 = Op$	en	0/15			15		1.5		0.75	1.5		1.5	mA
	$Pin 5 = V_{DD}$	••••	0/20			20		4		2	4		4	
	Pin 14 =Vss		0/5			5		5		0.04	5		150	
	or V <sub>DD</sub>	нсс	0/10			10		10		0.04	10		300	
	Pin $5 = V_{DD}$	Types	0/15			15		20		0.04	20		600	
		.,	0/20			20		100		0.08	100		3000	μА
			0/5			5		20		0.00	20		150	μ
		HCF	0/10			10		40		0.04	40		300	
		Types	0/10			15		80		0.04	80		600	
	Output		0/13	2.5		5	2	00	16	2.04	00	1 15	000	
'ОН	Drive		0/5	2.0		5 F	- 2		- 1.0	- J.Z		- 1.10		
	Current	HUU	0/10	4.0		5 10	- 0.64		- 0.51			- 0.36		
	Junion	Types	0/10	9.5		10	- 1.6		-1.3	- 2.6		- 0.9		
			0/15	13.5		15	- 4.2		- 3.4	- 6.8		- 2.4		mA
			0/5	2.5		5	- 1.53		- 1.36	- 3.2		- 1.1		
			0/5	4.6		5	- 0.52		- 0.44	- 1		- 0.36		
		Types	0/10	9.5		10	– 1.3		– 1.1	- 2.6		- 0.9		
			0/15	13.5		15	- 3.6		- 3.0	- 6.8		- 2.4	1	

#### STATIC ELECTRICAL CHARACTERISTICS (over recommended operating conditions)

\*  $T_{Low} = -55^{\circ}C$  for HCC device:  $-40^{\circ}C$  for HCF device. \*  $T_{High} = +125^{\circ}C$  for HCC device:  $+85^{\circ}C$  for HCF device. The Noise Margin for both "1" and "0" level is : 1V min. with  $V_{DD} = 5V$ , 2V min. with  $V_{DD} = 10V$ , 2.5V min. with  $V_{DD} = 15V$ .



			Т	Test Conditions				Value						
Symbol	Parameter		V	٧o	I <sub>0</sub>	$V_{DD}$	ΤL	ow*		25°C		T <sub>H</sub>	igh <sup>*</sup>	Unit
-			(V)	(V)	(µA)	(V)	Min.	Max.	Min.	Тур.	Max.	Min.	Max.	
I <sub>OL</sub>	Output	ЦСС	0/5	0.4		5	0.64		0.51	1		0.36		
	Sink	Types	0/10	0.5		10	1.6		1.3	2.6		0.9		
	Current	турсо	0/15	1.5		15	4.2		3.4	6.8		2.4		<b>س</b> ۸
			0/5	0.4		5	0.52		0.44	1		0.36		ma
		Types	0/10	0.5		10	1.3		1.1	2.6		0.9		
		Types	0/15	1.5		15	3.6		3.0	6.8		2.4		
V <sub>IH</sub>	Input High			0.5/4.5	< 1	5	3.5		3.5			3.5		
	Voltage			1/9	< 1	10	7		7			7		V
				1.5/13.5	< 1	15	11		11			11		
V <sub>IL</sub>	Input Low			4.5/0.5	< 1	5		1.5			1.5		1.5	
	Voltage			9/1	< 1	10		3			3		3	V
				13.5/1.5	< 1	15		4			4		4	
I <sub>IH</sub> , I <sub>IL</sub>	Input Leakage	HCC Types	0/18	Any In	nut	18		± 0.1		± 10 <sup>-5</sup>	± 0.1		± 1	μА
(except. pin 14)	HCF Types	0/15	,,	put	15		± 0.3		± 10 <sup>-5</sup>	± 0.3		± 1	ματ	
I <sub>OUT</sub>	3-state Leakage	HCC Types	0/18	0/18		18		± 0.4		± 10 <sup>-4</sup>	± 0.4		± 12	μА
	Current	HCF Types	0/15	0/15		15		± 1.0		± 10 <sup>-4</sup>	± 1.0		± 7.5	μι
CI	Input Capa	citance		Any In	put					5	7.5			рF

#### STATIC ELECTRICAL CHARACTERISTICS (continued)

\*  $T_{Low} = -55^{\circ}C$  for HCC device:  $-40^{\circ}C$  for HCF device. \*  $T_{High} = +125^{\circ}C$  for HCC device:  $+85^{\circ}C$  for HCF device. The Noise Margin for both "1" and "0" level is : 1V min. with  $V_{DD} = 5V$ , 2V min. with  $V_{DD} = 10V$ , 2.5V min. with  $V_{DD} = 15V$ .



Symbol	Paramotor	Test Conditions		Value			
Symbol	Falailletei		$V_{DD}$ (V)	Min.	Тур.	Max.	Unit
VCO SE	CTION						
PD	Operating Power	fo = 10 KHz R1 = 10 M $\Omega$	5		70	140	
	Dissipation	$R2 = \infty$ $V_{COIN} = \frac{V_{DD}}{V_{DD}}$	10		800	1600	μW
		2	15		3000	6000	
f <sub>max</sub>	Maximum Frequency	R1 = 10 KΩ C1 = 50 pF	5	0.3	0.6		
		$R2 = \infty$ $V_{COIN} = V_{DD}$	10	0.6	1.2		
			15	0.8	1.6		MHz
		$R1 = 5 K\Omega$ n $C1 = 50 pF$	5	0.5	0.8		
		$R2 = \infty$ $V_{COIN} = V_{DD}$	10	1	1.4		
			15	1.4	2.4		
	Center Frequency (f <sub>o</sub> ) and Frequency Range f <sub>max</sub> - f <sub>min</sub>	Programmable with exter	nal compone	nts R1,	R2 and (	C1	
	Linearity	$V_{COIN}=2.5V \pm 0.3$ R1=10 K $\Omega$	5		1.7		
		V <sub>COIN</sub> =5V <sup>± 1</sup> R1=100 KΩ	10		0.5		
		V <sub>COIN</sub> =5V <sup>± 2.5</sup> R1=400 KΩ	10		4		%
		$V_{COIN}$ =7.5V $\pm$ <sup>1.5</sup> R1=100 KΩ	15		0.5		
		$V_{COIN}=7.5V^{\pm 5}$ R1=1 M $\Omega$	15		7		
	Temperature Frequency		5		±0.12		
	Stability (no frequency		10		±0.04		
	offset) f <sub>min</sub> = 0		15		±0.015		%/°C
	Temperature Frequency		5		±0.09		
	Stability (frequency offset)		10		±0.07		
	f <sub>min</sub> ≠ 0		15		±0.03		
Vco	Output Duty Cycle		5, 10, 15		50		%
t <sub>THL</sub>	VCO Output Transition		5		100	200	
tт∟н	Time		10		50	100	ns
			15		40	80	
	Source Follower Output (demodulated Output): Offset Voltage V <sub>COIN</sub> - V <sub>DEM</sub>	R <sub>S</sub> > 10 KΩ	5, 10, 15		1.8	2.5	v
	Source Follower Output	R <sub>S</sub> =100 KΩ V <sub>COIN</sub> =2.5 <sup>±0.3</sup> V	5		0.3		
	(demodulated Output):	R <sub>S</sub> =300 KΩ V <sub>COIN</sub> =5 <sup>±2.5</sup> V	10		0.7		%
	Linearity	Rs=500 KΩ V <sub>COIN</sub> =7.5 <sup>±5</sup> V	15		0.9		
Vz	Zener Diode Voltage	I <sub>Z</sub> = 50 μA		4.45	5.5	7.5	V
Rz	Zener Dynamic Resistance	I <sub>Z</sub> = 1 mA			40		Ω
PHASE	COMPARATOR SECTION						
R14	Pin 14 (signal in) Input		5	1	2		
	Resistance		10	0.2	0.4		MΩ
			15	0.1	0.2		
	A.C. Coupled Signal Input	f <sub>in</sub> = 100 KHz sine wave	5	180	360		
	Voltage Sensitivity *		10	330	660		mV
	(peak to paek)		15	900	1800		

## **ELECTRICAL CARACTERISTICS** (T<sub>amb</sub> = 25 °C)



Symbol	Devementer	Test Conditions	;		Unit		
Symbol	Parameter		$V_{DD}$ (V)	Min.	Тур.	Max.	Unit
PHASE	COMPARATOR SECTION (cont'd)						
T <sub>PHL</sub>	Propagation Delay Time High to		5	225	450		
	Low Level Pins 14 to 13		10	100	200		ns
			15	65	130		
T <sub>PLH</sub>	Propagation Delay Time Low to		5		350	700	
	High, Level		10		150	300	ns
			15		100	200	
T <sub>PHZ</sub>	Propagation Delay Time 3-state		5		225	450	
High Level to High Impedance Pins 14 to 13	High Level to High Impedance		10		100	200	ns
			15		65	130	
T <sub>PLZ</sub>	Low Level to High Impedance		5		285	570	
			10		130	260	ns
			15		95	190	
t <sub>r</sub> , t <sub>f</sub>	Input Rise or Fall Time		5			50	
	Comparator Pin 3		10			1	μs
			15			0.3	
	Signal Pin 14		5			500	
			10			20	μs
			15			2.5	
$T_{THL},$	Transition Time		5		100	200	
T <sub>TLH</sub>			10		50	100	ns
			15		40	80	

### ELECTRICAL CHARACTERISTICS (continued)

\* For sine wave the frequency must be greater than  $10KH_Z$  for Phase Comparator II.



#### **DESIGN INFORMATION**

This information is a guide for approximating the values of external components for the **HCC/HCF 4046B** in a Phase-Locked-Loop system. The selected external components must be within the following ranges :

 $5k\Omega \le R1, R2, R_S \le 1M\Omega$   $C1 \ge 100pF$  at  $V_{DD} \ge 5V$   $C1 \ge 50pF$  at  $V_{DD} \ge 10V$ 

	USING PHASE	COMPARATOR I	USING PHASE COMPARATOR II			
CHARACTERISTICS	VCO WITHOUT	VCO WITH	VCO WITHOUT	VCO WITH		
	OFFSET R2 = ∞	OFFSET	OFFSET R2 = ∞	OFFSET		
VCO Frequency	1 max 1 0 1 min 1 0 1 min 1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0	Tmax to tmin VDD2 VCO INPUT VOLTAGE 5-1480	1 max 10 1 min VDD2	fmax to fmin YD02 YD0 VCO INPUT VOLTAGE 5-1460		
For No Signal Input	VCO in PLL System w frequency fo	vill Adjust to centre	VCO in PLL System v Operating Frequency	vill Adjust to Lowest f <sub>min</sub>		
Frequency Lock Range, 2 f <sub>L</sub>		$2 f_L = full VCO f_L = f_r$	frequency range <sub>nax</sub> - f <sub>min</sub>			
Frequency Capture Range, 2 f <sub>C</sub>	IN O R3 T1 = R3 C2 C2	O OUT (1),(2) $2f_{C} = \frac{1}{\pi} \sqrt{\frac{2\pi f_{L}}{r_{1}^{2}}}$ S-1483	(			
Loop Filter Component Selection		——————————————————————————————————————		= 1		
Phase Angle Between Signal and Comparator	90° at Centre Frequer 0° and 180° at ends o	icy ( $f_o$ ), approximating f lock range (2 $f_L$ )	Always 0° in lock			
Locks on Harmonics of Centre Frequency	Y	es	No			
Signal Input Noise Rejection	Hi	gh	Low			

\* G.S. Mosckytz "miniaturized RC filters using phase Lockedloop" BSTJ, may 1965



## Plastic DIP16 (0.25) MECHANICAL DATA

ЫМ		mm		inch				
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.		
a1	0.51			0.020				
В	0.77		1.65	0.030		0.065		
b		0.5			0.020			
b1		0.25			0.010			
D			20			0.787		
E		8.5			0.335			
е		2.54			0.100			
e3		17.78			0.700			
F			7.1			0.280		
Ι			5.1			0.201		
L		3.3			0.130			
Z			1.27			0.050		





ЫМ		mm		inch				
Dini.	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.		
А			20			0.787		
В			7			0.276		
D		3.3			0.130			
E	0.38			0.015				
e3		17.78			0.700			
F	2.29		2.79	0.090		0.110		
G	0.4		0.55	0.016		0.022		
Н	1.17		1.52	0.046		0.060		
L	0.22		0.31	0.009		0.012		
М	0.51		1.27	0.020		0.050		
N			10.3			0.406		
P	7.8		8.05	0.307		0.317		
Q			5.08			0.200		

## Ceramic DIP16/1 MECHANICAL DATA





## PLCC20 MECHANICAL DATA

DIM.		mm		inch				
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.		
А	9.78		10.03	0.385		0.395		
В	8.89		9.04	0.350		0.356		
D	4.2		4.57	0.165		0.180		
d1		2.54			0.100			
d2		0.56			0.022			
E	7.37		8.38	0.290		0.330		
е		1.27			0.050			
e3		5.08			0.200			
F		0.38			0.015			
G			0.101			0.004		
М		1.27			0.050			
M1		1.14			0.045			





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